TY Series Temperature and Humidity

Controller User Manual



Features:

 Adopt high accuracy digital temperature and humidity measurement sensor with temperature and humidity controller.

- 2. With temperature and humidity display, 4 loops control output
- With the function of PID heating, compressor delay cooling, ON/OFF humidification and dehumidification.

4. RS485 communication function.

KKTY-A01E-A0-20240910

14) Please don't knock or rub the panel with rigid thing.

15)The readers of this manual should have basic knowledge of electrical,control, computer and communications.

16)The illustration, example of data and screen in this manual is convenient to understand, instead of guaranteeing the result of the operation.

17) In order to use this product with safety for long-term, regular maintenance is necessary. The life of some parts of the equipments are by some restrictions, but the performance of some will change for using many years.

18)Without prior notice, the contents of this manual will be change. We hope these is no any loopholes, if you have questions or objections, please contact us.

▲ Caution of Install and Connection

1. Installation:

1) This product is used in the following environmental standards.

(IEC61010-1) [Overvoltage category II, Class of pollution 2]

 This product is used in the following scope: surrounding environment, temperature, humidity and environmental conditions.

Temperature: 0~50 $^{\rm C}$, Humidity: 45~85%RH; Environment condition: indoor warranty, the altitude is less than 2000m.

3) Please avoid using in the following places:

The place will be dew for changing temperature; with corrosive gases and flammable gas; with vibration and impact; with water, oil, chemicals, smoke and steam facilities with Dust, salt, metal powder; and with clutter interference, static electric and magnetic fields, noise; where has air conditioning or heating of air blowing directly to the site; where will be illuminated directly by sunlight; where accumulation of heat will happen caused by radiation.

4) On the occasion of the installation, please consider the following before installation.

In order to protect heat saturated, please ensure adequate ventilation space.

Please consider connections and environment, and ensure that the products below for more than 50mm space.

Please avoid to installed over the machine of the calorific value(Such as heaters,

transformer, semiconductor operations, the bulk resistance).

In order to improve the anti - interference performance and security, please try to stay away from high pressure machines, power machines to install.

Don't install on the same plate with high pressure machine and the product.

The distance should be more than 200mm between the product and power line. The power machine should be installated as far apart as possible

wer machine should be installated as far apart as

 \triangle Cable Caution

 The temperature and humidity sensor should be used with controller, and connection cable must be connected correctly according to the connection diagram.
 The temperature and humidity sensor is a digit I2C transmission. In order to improve

the reliability, the cable length needs to be within 3m. 3) In order to avoid the effect of noise,please put the input dignal away from meter cable,power cable,load cable to wiring. The instructions explain the instrument setting, connections, names and operations ect. Please read carefully before you use the TY Series Temperature and Humidity Controller. Please keep it properly for necessary reference.

Safe Caution:

▲ Warning 1) When the failure or abnormal of the products lead to a system of major accidents, please set the proper production circuit in the external.

2) Please don' t pulg in before completing all the wire. Otherwise it may lead to electric shock, fire, fault

3) Not allow to use outside the scope of product specification, otherwise it may lead to fire, fault.

4) Not allow to use in the place where is imflammable and explosive gas.

5) Do not touch power terminal and other high voltage part when power on,

otherwise you may get an electric-shock. 6) Do not disassemble, repair or alter this product,otherwise it may lead to electric shock, fire and malfunction.

△ Caution

1) The product should not be used in a nuclear facility and human life associated medical equipment.

2) The product may occur radio interference when it used at home. You should take adequate countermeasures.

3)The product get an electric shock protection through reinforced Insulation. when the product is embedded in the devices and wiring, please subject to the specification of embedded devices.

4)In order to prevent surge occurs,when using this product in the place of over 30m indoor wiring and wiring in outdoor,you need to set the proper surge suppression circuitry.

5) The product is produced based on mounting on the disk. In order to avoid to touch the wire connectors, please take the necessary measures on the product

6) Be sure to observe the precautions in this manual, otherwise there is a risk of a major injury or accident.

7) When wiring, please observe the local regulation.

8) To prevent to damage the machine and prevent to machine failure, the product is connected with power lines or large

9) Please don't put metal and wire clastic mixed with this product, otherwise it may lead to electric shock, fire, fault.

10) Please tighten screw torque according to the rules. If not, it may lead to electric shock and fire.

11) In order not to interfere with this products to dissipate heat, please don't plug casing around the cooling vent hole and equipment.

12) Please don't connect any unused terminal.

13)Please do the cleaning after power off, and use the dry cleaning cloth to wipe away the dirt. Please don't use desiccant, otherwise, it may casue the deformation or discoloration of the product.

4) In order to reduce the power cables and the load power cables on the effect of this product, please use noise filter in the place where easy to effect. You must install it on the grounding of the disk if you use the noise filter, and make the wiring to be shortest between noise filter output side and power connectors. Don't install fuse and switch on the wiring of noice filter output side, otherwise it will reduce the effect of noise filter.

5) It takes 5s from input power to output.If there is a place with interlocking actions circuit signal,please use timer relay.

6) Please use twisted pair with a shield for analog output line, to ensure the reliability of signal, if necessary.

7) Please use twisted pair with a shield for remote RS485 communication cable,and deal with the shield on the host side earth, to ensure the reliability of signal. You can add 120Ω termination matching resistor if necessary.

8) This product don't have the fuse; please set according to rated voltage 250V,rated current 1A if you need; fuse type:relay fuse.

9) Please use the suitable screw force and crimp terminal.

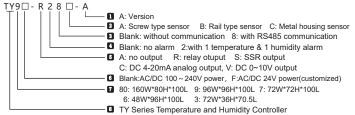
The screw terminal size: M3X8 (with 6.8X6.8 square base)

Recommended tightening torque: 0.4N.m

Proper cables: 0.25~1.65mm single cable/multiple core cable.

10) Please don't put the Crimp terminal or bare wire part contact with adjacent connector.

Model:



Note: (1) Size 3 doesn' t have alarm function, (2) For size 7, when it is SSR output, it doesn' t have alarm function.

Specification:

1) Parameters of temperature and humidity controller:

| Sampling Speed | 0.5, 1, 2, 4, 10 times (chosen by MPS menu) | | | |
|---|--|--|--|--|
| Relay Capacity | AC 250V /2A, Life of rated load> 100,000 times | | | |
| Power Supply AC/DC 100 ~ 240V (85-265V) | | | | |
| Power consumption | < 6VA | | | |
| Environment | Temperature of indoor: 0 ~ 50°C no condensation, Humidity < 85%RH, Altitude>2000m | | | |

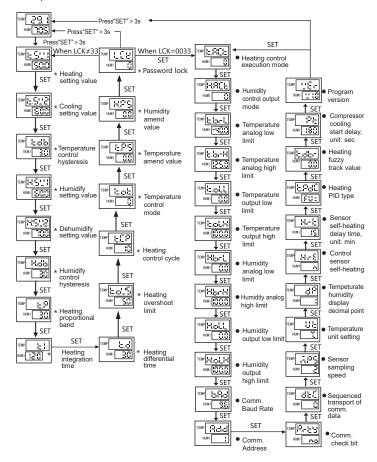
| Storage Environment | -10 ~ 60°C, no condensation | | | |
|--|---|--|--|--|
| SSR output | DC 24V pulse voltage, Load<30mA | | | |
| Current output | DC 4 ~ 20mA load< 500Ω, temperature drift 250PPM | | | |
| Communication | RS485, Modbus-RT protocol, max access 30 units | | | |
| Insulation impedance | input, output, power VS meter cover $> 20M\Omega$ | | | |
| ESD | IEC/EN61000-4-2 Contact ±4KV /Air ±8KV perf.Criteria B | | | |
| Pulse traip anti- interference | IEC/EN61000-4-4 ±2KV perf.Criteria B | | | |
| Surge immunity | IEC/EN61000-4-5 ±2KV perf.Criteria B | | | |
| Voltage drop & short interruption immunity | IEC/EN61000-4-29 0% ~ 70% perf.Criteria B | | | |
| Isolation strength | Signal, output and power: 2000VAC 1min, between lower than 60V circuits, DC500V,1min | | | |
| Total Weight | About 400g | | | |
| Shell material | The shell and panel frame PC/ABS (Flame Class UL94V-0) | | | |
| Panel material | PET(F150/F200) | | | |
| Power failure memory | 10 years, time of writing: 1 million times | | | |
| Panel Protection level | IP65(IEC60529) | | | |
| Safety Standard | IEC61010-1, Overvoltage category $\rm I\!I,$ pollution level 2, Level $\rm I\!I$ (Enhanced insulation) | | | |

2) Parameters of temperature and humidity sensor:

| Power Supply | Minimum value 3.3V, Maximum value 5.5V | | | | |
|----------------------------------|--|--|--|--|--|
| Temperature Measurement Range | Physical range: -40.0 ~ 125.0 °C, safe range: -40 ~ 80.0 °C, resolution: 0.1 °C | | | | |
| Humidity Measurement Range | 0.0 ~ 100.0% RH; Resolution: 0.1 C RH | | | | |
| Temperature Accuracy | Within 0.0 ~ 80.0°C Typical value ±0.2°C Maximum value: ±0.4°C | | | | |
| Humidity Accuracy | within 0.0 ~ 90.0%RH Typical value: ±2%RH Maximum value: ±2.5%RH | | | | |
| Wire Length | Standard: 2M; The maximum length of the lead with the controller is less than 3 meters | | | | |
| | | | | | |

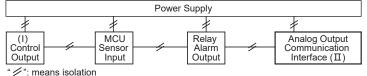
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VII. Operation & menu



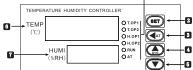
"*" : common menu parameter

3) Isolation diagram



Notes: When the output between (I)&(II) is SSR output, it is not insulated; when it is relay output, it is insulated.

Name of Universal Panel



| No. | Symbol | Name | Function | | | | |
|------|-------------------------------------|-------------------------------------|---|--|--|--|--|
| | T.OP1 | T.OP1 indicate light (red) | Heating output indicator, when the output is ON, the light is on | | | | |
| | T.OP2 | T.OP2 indicate light (red) | Cooling output indicator, when the output is ON, the light is on | | | | |
| 1 | H.OP1 | H.OP1 indicate light (red) | Humidifying output indicator, when the output is ON, the light is on | | | | |
| | H.OP2 H.AL1 indicate light (red) | | Dehumidifying output indicator, when the output is ON, the light is on | | | | |
| | RUN | Control- run indicate light (green) | It is runing when the light is on, it stops running when the ligh is off. | | | | |
| AT A | | AT indicate light (green) | Heating PID auto-tuning indicate light,it indicates auto-tuning status when lighting on | | | | |
| 2 | SET | SET function key | Menu key/confirm key, to enter or exit modified mode or confirm modified parameters | | | | |
| 3 | | Shift AT key | Activation/shift key/AT auto-tuning key,long press to enter/exit auto-tuning under measure control mode | | | | |
| 4 | 4 Increase key /R/S | | Increase key, long press it to shift RUN/STOP mode under measure control mode. | | | | |
| 5 | | | Decrease key | | | | |
| 6 | | | Temperature measurement value or parameter code display window | | | | |
| 7 | HUMI | Humidity Display Window(green) | Humidity measurement value or parameter value display window | | | | |
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a. In the normal measurement control mode after power on, long press " SET " key for more than 3s to enter the menu parameter view mode.

- b. In the menu view mode, short press " SET " key to cycle to view the common menu parameters.
- c. In the menu view mode, short press the " ◀ at " key to flash the displayed menu parameter value to enter the parameter modification mode, and each short press can move one bit to the left; this cycle.
- d. In the parameter modification mode, each short press the " ▲ " or " ▼ " key can increase the flashing data bit by one or minus one.
- e. Under the parameter modify mode, after the parameters are modified, short press the " SET " key to ensure to save the parameters, and exit the menu view mode.

f. In the normal measurement control mode, long press " ◄ " key for more than 3 sec to enter the heating PID auto-tuning state. The auto-tuning TEMP display value needs

to be smaller than the T.SV1 value. h. Under the normal measurement control mode, long press " ▲ " key for more than

3 sec to enter or exit the Run or Stop mode.

2) Menu illustration

| , | | | | |
|-----|--|--|----------------------------------|--------------------|
| No. | Menu Name | Description | Setting Range | Factory Setting |
| 1 | TEMP(°C) | Temperature measured value, unit °C or °F | | |
| 2 | HUMI (%RH) | Humidity measured value, unit %RH | | |
| 3 | T.SV1 | Heating setting value, when OT= 0 or P=0, it is ON/OFF control, not PID control, when TEMP < T.SV1 - T.DB, heating output is on; when TEMP ≥ T.SV1, it stops heating. When it is set as PID heating control, this value is PID control target set value. | -40.0~125.0 or -40.0~257.0 | 50.0 |
| 4 | T.SV2 | Cooling setting value, The cooling modes include compressor cooling and ON OFF cooling. Compressor cooling method when TEMP ≥ T.SV2, the PT delay time is reached and the cooling output is started. When it is in ON OFF mode, the cooling output is directly started.Stop cooling output when TEMP <t.sv2-t.db.< td=""><td>-40.0~125.0 or -40.0~257.0</td><td>60.0</td></t.sv2-t.db.<> | -40.0~125.0 or -40.0~257.0 | 60.0 |
| 5 | T.DB | Temperature control hysteresis, it is used in concert with temperature control. Note: when the value is negative, it will be treated as an absolute value. | -30.0 ~ 30.0 | 3.0 |
| 6 | Humidity setting value, when it is set as ON/OFF humidifying control, when HUMI <h.sv1-h.db, humidifying output is on, when HUMI≥H.SV1, it stops humidifying output.</h.sv1-h.db, | | 0.0 ~ 100.0 | 60.0 |
| 7 | H.SV2 H.SV2 H.SV2 H.SV2 H.SV2 H.SV2 H.SV2-H.DB, dehumidifying output is on, when HUMI <h.sv2.h.db, dehumidifying output is on, when HUMI<h.sv2, it stops dehumidifying output.</h.sv2, </h.sv2.h.db, | | 0.0 ~ 100.0 | 70.0 |
| 8 | H.DB | Humidity control hysteresis, it is used in concert with humidity control. Note: when the value is negative, it will be treated as an absolute value. | -30.0 ~ 30.0 | 3.0 |

| No. | Menu Name | Description | Setting Range | Factory Setting |
|----------|--|---|------------------|--------------------|
| 9 | T.P | 0~9999 | 30 | |
| 10 | T.I | 0~9999 | 120 | |
| 11 | T.D | 0~9999 | 30 | |
| 12 T.OVS | | Heating overshoot limit, during the PID control, when TEMP (measured value) > T.SV1 (set value) + T.OVS (overshoot), force to close output. Note: the smaller this value is, the smaller the PID adjustment range will be, the worse the control stability will be. Please set the appropriate value according to the actual situation. | 0~100.0 | 5.0 |
| 13 | T.CP | Heating control cycle, 1 is SSR control output, 4 ~ 255 is relay control output, unit: second | 1~200 | 10 |
| 14 | T.OT | Temperature control mode, 0: ON/OFF heating; 1: ONOFF cooling; 2: PID heating | 0~2 | 0 |
| 15 | T.PS | Temperature amend value, display value= measured value + amend value | -30.0~ 30.0 | 0.0 |
| 16 | 16 H.PS Humidity amend value, display value= mea value + amend value. | | -30.0~ 30.0 | 0.0 |
| 17 | LCK | Lock function; 010: menu set value can be checked only, cannot be modified. 0033: enter to advanced menu. | 0~9999 | 0 |
| 18 | T.ACT | 0~3 | 0 | |

| 19 | H.ACT | Humidifyiny control output mode: 0: relay or SSR control output; 1, 2: reserve; 3: 4~20mA analog output (size 3 without this function) | 0~3 | 0 |
|--------|---|--|--------------------------------|-------|
| 20 | T.BRL | Temperature analog output low limit, note: when T.BRL > T.BRH, it is inverted analog output. | Refer to T.SV1 | -40.0 |
| 21 | T.BRH | Temperature analog output high limit, note: when T.BRH < T.BRL, it is inverted analog output. | Refer to T.SV1 | 125.0 |
| 22 | T.OLL | Temperature current output low limit, note: this value must be smaller than T.OLH. | -5.0 ~ 100.0 | 0.0 |
| 23 | T.OLH | Temperature current output high limit, note: this value must be greater than T.OLL. | 0.0 ~ 105.0 | 100.0 |
| 24 | H.BRL | Humidity analog output low limit, note: when H.BRL > H.BRH, it is inverted analog output. | 0.0~ 100.0 | 0.0 |
| 25 | H.BRH | Humidity analog output high limit, note: when H.BRH < H.BRL, it is inverted analog output. | 0.0~ 100.0 | 100.0 |
| 26 | H.OLL | Humidity current output low limit, note: this value must be smaller than H.OLH. | -5.0~ 100.0 | 0.0 |
| 27 | H.OLH | 0.0~ 105.0 | 100.0 | |
| 28 | 8 BAD RS485 communication baud rate 0: 4800; 1: 9600; 2: 19200 | | 0 ~ 2 | 9.6 |
| 29 | ADD | Communication Address | 0 ~ 255 | 1 |
| 30 | PRTY | Communication check bit setting, 0: NO check,1: ODD check, 2: EVEN check | 0 ~ 2 | NO |
| 31 DTC | | Communication data transport sequence 000; 1st, 3rd are function reserved, 2nd bit is byte sequence exchange | Refere to comm. procotol | 0 |
| 32 | 2 MPS Sampling speeds: 0: 0.5 times, 1: 1 time, 2: 2 times, 3: 4 times, 4: 10 times | | 0 ~ 4 | 2 |
| 33 | 3 UT Temperature unit setting 25: °C, 26 : °F. Note: the unit setting is only for the temperature measurement signal. | | C/F | °C |
| 34 | DP | Decimal point setting, reserve decimal bit | 0 ~ 1 | 1 |
| 35 | HRE | Control sensor self-heating, when set to Y, the sensor starts to self-heating | N/Y | N |
| 36 | HRT | Sensor self-heating delay time, unit: minutes | 0 ~ 200 | 15 |

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| 37 | T.PDC | Heating PID type. 0:FUZ fuzzy PID control, 1: STD standard PID control | FUZ/STD | FUZ |
|----|-------|---|----------|-----|
| 38 | T.DTR | TEMP fuzzy tracking value, properly set this value on some occasions, it can get a more stable control display value, this value is independant from the actual measured value. Note: after setting this value, when T.SV is equal to TEMP value, the control output operation is subject to the actual measured value. Set it as 0 to close this function. The temperature unit is: °C or °F. | 0 ~ 2.0 | 0.0 |
| 39 | PT | Compressor cooling start delay time, unit: seconds | 0 ~ 9999 | 180 |
| 40 | VER | Software Version | | |

Key function operation

1. Run and stop mode operation

1) Under the measure mode, long press \clubsuit to enter STOP mode; and the RUN indication light will be off; long press \clubsuit to enter the run mode.

Under the run mode, all the output will work accoring to the specified requirements, and will stop working under the stop mode.

2. PID parameter confirmation and auto-tuning operation

1) The default PID parameter of factory setting is not suitable for the using occasion; please use auto-tuning function to get the suitable PID parameter.

2) It will control output shortly after power is turned on, the product can be set to the stop mode first in order not affect the auto-tuniing effect. Or temporarily disconnect the control output load power. Regardless of the operation, ensure that the T.SV1 value is greater than the current TEMP value and the larger the difference, the better.

Set the PID type and the T.SV1 value, the factory default setting is fuzzy PID.

4) Set the PID control, when the output is 4-20mA, please set the output limit of OLL and OLH to the appropriate range factory default:OLL=0%,OLH=100%

5) When the TEMP<H.SV1 value is at normal room temperature, exit the stop mode and connect the load power, and immediately press the " \blacktriangleleft " key to enter the auto-tuning mode. At this time, the AT indicator lights is on.

6) The auto-tuning will take a certain amount of time, in order not to affect the auto-tuning result, please do not modify the parameter or power off in the auto-tuning mode.

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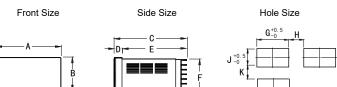
7) When the AT light is off, it will exit the auto-tuning. The PID parameter will update automatically, the automatic and accurate control will be performed.

8) During auto-tuning, long press " ◄ " key, measure beyond the range, display abnormally, shift to Stop status, power-off etc will stop the auto-tuning.

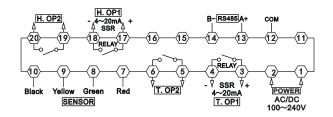
9) Note: In the place with current output limit, it may not get the best PID parameters even after auto-tuning.

10) Experienced users can set a proper PID parameter accoding to their experience.

Dimension and installation size



| Mode | Α | В | С | D | Е | F | G | H(Min) | J | K(Min) |
|-------------|-----|----|------|-----|------|------|-------|--------|------|--------|
| 3:(72*36) | 72 | 36 | 70.5 | 6.5 | 64 | 32 | 68 | 25 | 33 | 25 |
| 6:(96*48) | 48 | 96 | 97.5 | 9 | 88.5 | 89.5 | 45 | 25 | 92 | 25 |
| 7:(72*72) | 72 | 72 | 97.5 | 9 | 88.5 | 67 | 67.5 | 25 | 67.5 | 25 |
| 8:(48*96) | 96 | 48 | 97.5 | 9 | 88.5 | 44.5 | 92 | 25 | 45 | 25 |
| 9:(96*96) | 96 | 96 | 97.5 | 9 | 88.5 | 91.5 | 92 | 25 | 92 | 25 |
| 80:(160*80) | 160 | 80 | 96 | 13 | 83 | 75.5 | 155.5 | 30 | 76 | 30 |



XI. Checking methods of simple fault

| Display | Methods |
|----------|--|
| Err/HHHH | Checks whether the sensor error or over the measuring range; whether the input disconnection and whether the sensor damages, working environment temperature inner the range of sensor measurement range |

XII. Communication Protocol

Meter adopt RS485 Modbus-RTU communication protocol, RS485 half duplex communication. Read function code: 0x03;write function code: 0x10/ 0x06. Adpots 16 digit CRC check, the meter does not return for error check.

Data Frame Format

| Start Bit | Data Bit | Stop Bit | Check Bit |
|-----------|----------|----------|----------------------|
| 1 | 8 | 1 | Setting in PRTY menu |

Abnormal communication processing: When abnormal response, put 1 on the highest bit of function code. For example: Host request function code 0x03,and slave response function code should be 0x83.

Error code:

0x01--- llegal function: the function code sent from host is not supported by meter. 0x02--- llegal add.: the register address designated by host beyond the address range of meter.

0x03--- Illegal data: date value sent from host exceeds the corresponding data range of meter. Communication cycle:

Communication cycle is the time from host request to slave response data. For example: communication cycle= time of request data sending +slave preparation time + response delay time + response return time E.g.: 9600 baud rate: communication cycle of single measured data \ge 250ms.

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Data location Error Answer (For example: host request ADD is 0x200F)

| | | Slave Abn | ormal Answer | (read mu | ulti-regis | ter) | | | |
|-------------------------|-------------------|-----------------------------------|------------------|------------|------------|----------------------------|-------------------|---------------|--|
| | 1 | 2 | 3 | 8 | | | 9 | | |
| Meter ADD Function Code | | Function Code | Error Code | XCRC (| Code Lo | w Bit 🛛 🚿 | CRC Code High Bit | | |
| C |)x01 | 0x90 | 0x03 | | 0X0C | | 0 | x01 | |
| Mete | er Parame | ters ADD Reflecti | on Form | | | | | | |
| No. | ADD Reflection | Vai | iable Name | | Register | Numerical Magnification | Read/ on Write | Remark | |
| 1 | 0x2000 | TEMP Measure | d Value | | 1 | 0.1/1 | R | Decided by DF | |
| 2 | 0x2001 | HUMI Measure | d Value | | 1 | 0.1/1 | R | Decided by DF | |
| 3 | 0x2002 | Temperature ar Point Setting D | | ecimal | 1 | 1 | R/W | | |
| 4 | 0x2003 | Heating Set Val | ue T.SV1 | | 1 | 0.1 | R/W | | |
| 5 | 0x2004 | Cooling Set Val | ue T.SV2 | | 1 | 0.1 | R/W | | |
| 6 | 0x2005 | Temperature C | ontrol Hystere | sis T.DB | 1 | 0.1 | R/W | | |
| 7 | 0x2006 | Humidity Set V | alue H.SV1 | | 1 | 0.1 | R/W | | |
| 8 | 0x2007 | Dehumidity Se | | 2 | 1 | 0.1 | R/W | | |
| 9 | 0x2008 | Humidity Cont | rol Hysteresis | H.DB | 1 | 0.1 | R/W | | |
| 10 | 0x2009 | Temperature Ar | mend Value T | PS | 1 | 0.1 | R/W | | |
| 11 | 0x200A | Humidity Amen | d Value H.PS | | 1 | 0.1 | R/W | | |
| 12 | 0x200B | Temperature Ar T.BRL | nalog Output I | Low Limit | 1 | 0.1 | R/W | | |
| 13 | 0x200C | Temperature Ar T.BRH | alog Output H | High Limit | 1 | 0.1 | R/W | | |
| 14 | 0x200D | Temperature Cu T.OLL | urrent Output | Low Limit | 1 | 0.1 | R/W | | |
| 15 | 0x200E | Temperature Cu T.OLH | Irrent Output | High Limit | 1 | 0.1 | R/W | | |
| 16 | 0x200F | Humidity Analo H.BRL | g Output Low | Limit | 1 | 0.1 | R/W | | |
| 17 | 0x2010 | Humidity Analo H.BRH | og Output High | n Limit | 1 | 0.1 | R/W | | |
| 18 | 0x2011 | Humidity Curr H.OLL | ent Output Lo | w Limit | 1 | 0.1 | R/W | | |
| 19 | 0x2012 | Humidity Curr H.OLH | ent Output Hi | gh Limit | 1 | 0.1 | R/W | | |
| | | | | Reserve | | | | | |
| 20 | 0x2100 | Heating Proport | tional Coefficie | ent T.P | 1 | 1 | R/W | | |
| 21 | 0x2101 | Heating Integra | l Time T.I | | 1 | 1 | R/W | | |
| 22 | 0x2102 | Heating Differen | ntial Time T.D | | 1 | 1 | R/W | | |
| 23 | 0x2103 | Heating Oversh | oot Limit T.O | /S | 1 | 0.1 | R/W | | |
| 24 | 0x2104 | Heating Control | Cvcle T.CP | | 1 | 1 | R/W | | |

1. Read Multi-register

E.g.: Host reads the integer T.SV1 (set value 50.0) The address code of T.SV1 is 0 x 2003. Because T.SV is integer (2 byte), seizes 1 data register. The memory code of decimal integer 50.0x10=500 is 0x01F4.

| | Host Request (read multi-register) | | | | | | | | | | | |
|--------------|---|------|------|---------------------|----|----|----|-----|------|-------------------------------|--|--|
| 1 | 2 | 3 | 4 | 5 | | 6 | 6 | 7 | | 8 | | |
| | | | | | | | | | | <pre>%CRC Code High Bit</pre> | | |
| 0x01 | 0x03 | 0x20 | 0x03 | 0x03 0x00 0x01 0x7F | | | | | 0xCA | | | |
| | Slave Normal Answer (read multi-register) | | | | | | | | | | | |
| 1 | 1 2 3 4 5 6 7 | | | | | | | | | | | |
| Meter Add | Meter Add Function Code Data Byte Data High Bit Data Low Bit %CRC Code Low Bit %CRC Code High Bit | | | | | | | | | | | |
| 0x01 | 0x03 | 0x02 | 0> | :01 | 0X | F4 | 02 | XB8 | 0X53 | | | |
| Eurotic | | | | | | | | | | | | |

Function code abnormal answer (e.g.: host request ADD is 0x 0x2010) Slave Abnormal Answer (read multi-register)

| I | Slave Abhomal Answer (Teau multi-register) | | | | | | | | | | | |
|---|--|---------------|------------|-------------------|-------------------|--|--|--|--|--|--|--|
| | 1 | 2 | 3 | 8 | 9 | | | | | | | |
| | Meter ADD | Function Code | Error Code | XCRC Code Low Bit | CRC Code High Bit | | | | | | | |
| | 0x01 | 0x83 | 0x02 | 0XC0 | 0XF1 | | | | | | | |

2. Write Multi-register E.g.: Host writes the integer H.SV1 (set value 50.0) The address code of H.SV1 is 0x2003, because SV is integer (2 byte), seizes 1 data register. The hexadecimal memory code of decimal integer 50.0X10=500 is 0x01F4

| | Host Request (Write Multi-Register) | | | | | | | | | | | | |
|--------------|---|--------------------------|-------------------------|----------------------------------|------------------------|-------------------------------|--------------------------|---------------------|-----------------|-------------------------|------|-------------------------------|--|
| 1 | 2 | 3 | 4 | | 5 | 6 | 7 | 8 | 9 | 10 |) | 11 | |
| Meter ADD | Function Code | Start ADD High Bit | Start ADD Low Bit | Len | a Byte gth n Bit | Data Byt Length Low Bit | e Data Byte Length | Data High Bit | Data Low Bit | %CRC Code Low Bit | | <pre>%CRC Code High Bit</pre> | |
| 0x01 | 0x10 | 0x20 | 0x03 | 03 0x00 0x01 0x02 0x01 0xF4 0x87 | | | | | | 37 | 0XB6 | | |
| | Slave Normal Answer(Write Multi-Register) | | | | | | | | | | | | |
| 1 | 2 | 3 | 4 | | | 5 | 6 | | 7 | | | 8 | |
| Meter Add | Meter Function Start ADD Start ADD Data Byte Data byte %CRC Code %CRC Code Add Code High Bit Low Bit Length High Bit Length Low Bit Low Bit High Bit | | | | | | | | | | | | |
| 0x01 | 0x01 0x10 0x20 0x03 0x00 0x01 0xFA 0x09 | | | | | | | | | | | 0x09 | |
| Host w | rite single | -register | SV (set | value | e 150) | | | | | | | | |

| | Host Request (write single-register) | | | | | | | | | | | |
|-----------------|--|-----------------|----------------|------------------------------|-----------------|----------------------|-----------------------|--|--|--|--|--|
| 1 2 3 4 5 6 7 8 | | | | | | | | | | | | |
| Meter ADD | Function Code | ADD High Bit | ADD Low Bit | Data Byte Length High Bit | Data Low Bit | %CRC Code Low Bit | %CRC Code High Bit | | | | | |
| 0x01 | 0x06 | 0x20 | 0x03 | 0x01 | 0xF4 | 0x72 | 0x1D | | | | | |
| | Slave Normal Answer (write single-register) | | | | | | | | | | | |
| 1 2 3 4 5 6 7 8 | | | | | | | | | | | | |
| Meter | | ADD High | | Data Byte Length | Data Low | %CRC Code | | | | | | |
| ADD | ADD Code Bit Bit High Bit Bit Low Bit High Bit | | | | | | | | | | | |
| 0x01 | 0x06 | 0x20 | 0x03 | 0x01 | 0xF4 | 0x72 | 0x1D | | | | | |

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| 25 | 0x2105 | Temperature Control Mode T.OT | 1 | 1 | R/W | Remark | | | | |
|----|--------|--|---|-----|-----|---|--|--|--|--|
| 26 | 0x2106 | Heating Control Output Mode T.ACT | 1 | 1 | R/W | | | | | |
| 27 | 0x2107 | Humidifing Control Output Mode H.ACT | 1 | 1 | R/W | | | | | |
| 28 | 0x2108 | Run/Stop Operation | 1 | 1 | R/W | 1: RUN 2: STOP 3: Start Auto-tuning 4: Stop Auto-tuning | | | | |
| 29 | 0x2109 | Temperature Unit Setting UNIT | 1 | 1 | R/W | | | | | |
| 30 | 0x210A | Sensor Sampling Speed MPSL | 1 | 1 | R/W | | | | | |
| 31 | 0x210B | Sensor Self-heating HRE | 1 | 1 | R/W | | | | | |
| 32 | 0x210C | Sensor Self-heating Delay Time HRT | 1 | 1 | R/W | | | | | |
| 33 | 0x210D | Compressor Cooling Start Delay Time PT | 1 | 1 | R/W | | | | | |
| 34 | 0x210E | Communication Address ADD | 1 | 1 | R/W | | | | | |
| 35 | 0x210F | Communication Baud Rate BAD | 1 | 1 | R | | | | | |
| 36 | 0x2110 | Communication Data Transport Sequence DTC | 1 | 1 | R | Note(2) | | | | |
| 37 | 0x2111 | Communication Check Bit Setting PRTY | 1 | 1 | R | | | | | |
| 38 | 0x2112 | Heating PID Type T.PDC | 1 | 1 | R | | | | | |
| 39 | 0x2113 | TEMP Fuzzy Tracking Value T.DTR | 1 | 0.1 | R | | | | | |
| 40 | 0x2114 | Lock Function LCK | 1 | 1 | R | | | | | |
| 41 | 0x2115 | Temperature and Humidity Controller Status STATUS | 1 | 1 | R | Note(1) | | | | |
| 42 | 0x2116 | Temperature and Humidity Controller Name NAME | 1 | 1 | R | | | | | |

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | | |
|----|-----|-----|----|-------|-------|-------|-------|--|--|--|
| | ERR | RUN | AT | H.OP2 | H.OP1 | T.OP2 | T.OP1 | | | |
| | | | | | | | | | | |

Note(2): Sequenced transport and response delay of DTC communication data

. □ — Reserve DTC: 🛛 Ľ

- Sequenced transport byte: 0=1,2 1=2, 1

-Reserve

%16 digits CRC check code get C program unsigned int Get_CRC(uchar *pBuf, uchar num)

unsianed i.i:

unsigned i,j, unsigned int wCrc = 0xFFFF; for(i=0; i<num; i++)

{

wCrc ^= (unsigned int)(pBuf[i]); for(j=0; j<8; j++)

if(wCrc & 1){wCrc >>= 1; wCrc ^= 0xA001; }

else

wCrc >>= 1; }

return wCrc;

}

}